

What is an Operating System

1.1 Introduction: An *operating system* (OS) is software that manages computer hardware and software resources and provides common services for computer programs. The operating system is an essential component of the system software in a computer system. Application programs usually require an operating system to function. It is the operating system that makes life easy for mankind as people utilize their computers. Users do not have to be concerned with the internal workings of the computer because the OS monitors and controls all of the programming automatically

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For hardware functions such as input and output and memory allocation, the operating system acts as an intermediary between programs and the computer hardware,^[2] although the application code is usually executed directly by the hardware and will frequently make a system call to an OS function or be interrupted by it. Operating systems can be found on almost any device that contains a computer—from cellular phones and video game consoles to supercomputers and web servers.

Examples of popular modern operating systems include Android, BSD, iOS, Linux, OS X, QNX, Microsoft Windows,^[3] Windows Phone, and IBM z/OS. All these examples, except Windows, Windows Phone and z/OS, share roots in UNIX.

1.2 Types of Operating Systems.

Real-time

A real-time operating system is a multitasking operating system that aims at executing real-time applications. Real-time operating systems often use specialized scheduling algorithms so that they can achieve a deterministic nature of behavior. The main objective of real-time operating systems is their quick and predictable response to events. They have an event-driven or time-sharing design and often aspects of both. An event-driven system switches between tasks based on their priorities or external events while time-sharing operating systems switch tasks based on clock interrupts.

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Multi-user

A multi-user operating system allows multiple users to access a computer system at the same time. Time-sharing systems and Internet servers can be classified as multi-user systems as they enable multiple-user access to a computer through the sharing of time. Single-user operating systems have only one user but may allow multiple programs to run at the same time.¹

Multi-tasking vs. single-tasking

A multi-tasking operating system allows more than one program to be running at the same time, from the point of view of human time scales. A single-tasking system has only one running program. Multi-tasking can be of two types: pre-emptive and co-operative. In pre-emptive multitasking, the operating system slices the CPU time and dedicates one slot to each of the programs. Unix-like operating systems such as Solaris and Linux support pre-emptive multitasking, as does Amiga OS. Cooperative multitasking is achieved by relying on each process to give time to the other processes in a defined manner. 16-bit versions of Microsoft Windows used cooperative multi-tasking. 32-bit versions of both Windows NT and Win9x, used pre-emptive multi-tasking. Mac OS prior to OS X used to support cooperative multitasking.

Distributed

A distributed operating system manages a group of independent computers and makes them appear to be a single computer. The development of networked computers that could be linked and communicate with each other gave rise to distributed computing. Distributed computations are carried out on more than one machine. When computers in a group work in cooperation, they make a distributed system.

Templated

In an o/s, distributed and cloud computing context, templating refers to creating a single virtual machine image as a guest operating system, then saving it as a tool for multiple running virtual machines (Gagne, 2012, p. 716). The technique is used both in virtualization and cloud computing management, and is common in large server warehouses. ^[4]

Embedded

Embedded operating systems are designed to be used in embedded computer systems. They are designed to operate on small machines like PDAs with less autonomy. They are able to operate with a limited number of resources. They are very compact and extremely efficient by design. Windows CE and Minix 3 are some examples of embedded operating systems.

1.3 History

Early computers were built to perform a series of single tasks, like a calculator. Basic operating system features were developed in the 1950s, such as resident monitor functions that could automatically run different programs in succession to speed up processing. Operating systems did not exist in their modern and more complex forms until the early 1960s. Hardware features were added, that enabled use of runtime libraries, interrupts, and parallel processing. When personal computers became popular in the 1980s, operating systems were made for them similar in concept to those used on larger computers.

In the 1940s, the earliest electronic digital systems had no operating systems. Electronic systems of this time were programmed on rows of mechanical switches or by jumper wires on plug boards. These were special-purpose systems that, for example, generated ballistics tables for the military or controlled the printing of payroll checks from data on punched paper cards. After programmable general purpose computers were invented, machine languages (consisting of strings of the binary digits 0 and 1 on punched paper tape) were introduced that sped up the programming process (Stern, 1981).

OS/360 was used on most IBM mainframe computers beginning in 1966, including computers utilized by the Apollo program.

In the early 1950s, a computer could execute only one program at a time. Each user had sole use of the computer for a limited period of time and would arrive at a scheduled time with program and data on punched paper cards and/or punched tape. The program would be loaded into the machine, and the machine would be set to work until the program completed or crashed. Programs could generally be debugged via a front panel using toggle switches and panel lights. It is said that Alan Turing was a master of this on the early Manchester Mark 1 machine, and he was already deriving the primitive conception of an operating system from the principles of the Universal Turing machine.

Later machines came with libraries of programs, which would be linked to a user's program to assist in operations such as input and output and generating computer code from human-readable symbolic code. This was the genesis of the modern-day operating system. However, machines still ran a single job at a time. At Cambridge University in England the job queue was at one time a washing line from which tapes were hung with different colored clothes-pegs to indicate job-priority.¹

Mainframes

Through the 1950s, many major features were pioneered in the field of operating systems, including batch processing, input/output interrupt, buffering, multitasking, spooling, runtime libraries, link-loading, and programs for sorting records in files. These features were included or not included in application software at the option of application programmers, rather than in a separate operating system used by all applications. In 1959, the SHARE Operating System was released as an integrated utility for the IBM 704, and later in the 709 and 7090 mainframes, although it was quickly supplanted by IBSYS/IBJOB on the 709, 7090 and 7094.

During the 1960s, IBM's OS/360 introduced the concept of a single OS spanning an entire product line, which was crucial for the success of the System/360 machines. IBM's current mainframe operating systems are distant descendants of this original system and applications written for OS/360 can still be run on modern machines.

OS/360 also pioneered the concept that the operating system keeps track of all of the system resources that are used, including program and data space allocation in main memory and file space in secondary storage, and file locking during update. When the process is terminated for any reason, all of these resources are re-claimed by the operating system.

The alternative CP-67 system for the S/360-67 started a whole line of IBM operating systems focused on the concept of virtual machines. Other operating systems used on IBM S/360 series mainframes included systems developed by IBM: COS/360 (Compatibility Operating System), DOS/360 (Disk Operating System), TSS/360 (Time Sharing System), TOS/360 (Tape Operating System), BOS/360 (Basic Operating System), and ACP (Airline Control Program), as well as a few non-IBM systems: MTS (Michigan Terminal System), MUSIC (Multi-User System for Interactive Computing), and ORVYL (Stanford Timesharing System).

Control Data Corporation developed the SCOPE operating system in the 1960s, for batch processing. In cooperation with the University of Minnesota, the Kronos and later the NOS operating systems were developed during the 1970s, which supported simultaneous batch and timesharing use. Like many commercial timesharing systems, its interface was an extension of the Dartmouth BASIC operating systems, one of the pioneering efforts in timesharing and programming languages. In the late 1970s, Control Data and the University of Illinois developed the PLATO operating system, which used plasma panel displays and long-distance time sharing networks. Plato was remarkably innovative for its time, featuring real-time chat, and multi-user graphical games.

In 1961, Burroughs Corporation introduced the B5000 with the MCP, (Master Control Program) operating system. The B5000 was a stack machine designed to exclusively support high-level languages with no machine language or assembler, and indeed the MCP was the first OS to be written exclusively in a high-level language – ESPOL, a dialect of ALGOL. MCP also introduced many other ground-breaking innovations, such as being the first commercial implementation of virtual memory. During development of the AS400, IBM made an approach to Burroughs to licence MCP to run on the AS400 hardware. This proposal was declined by Burroughs management to protect its existing hardware production. MCP is still in use today in the Unisys ClearPath/MCP line of computers.

UNIVAC, the first commercial computer manufacturer, produced a series of EXEC operating systems. Like all early main-frame systems, this batch-oriented system managed magnetic drums, disks, card readers and line printers. In the 1970s, UNIVAC produced the Real-Time Basic (RTB) system to support large-scale time sharing, also patterned after the Dartmouth BC system.

General Electric and MIT developed General Electric Comprehensive Operating Supervisor (GECOS), which introduced the concept of ringed security privilege levels. After acquisition by Honeywell it was renamed General Comprehensive Operating System (GCOS).

Digital Equipment Corporation developed many operating systems for its various computer lines, including TOPS-10 and TOPS-20 time sharing systems for the 36-bit PDP-10 class systems. Before the widespread use of UNIX, TOPS-10 was a particularly popular system in universities, and in the early ARPANET community.

From the late 1960s through the late 1970s, several hardware capabilities Early systems had utilized microprogramming to implement features on their systems in order to permit different underlying computer architectures to appear to be the same as others in a series. evolved that allowed similar or ported software to run on more than one system. In fact, most 360s after the 360/40 (except the 360/165 and 360/168) were microprogrammed implementations.

The enormous investment in software for these systems made since the 1960s caused most of the original computer manufacturers to continue to develop compatible operating systems along with the hardware. Notable supported mainframe operating systems include:

- Burroughs MCP – B5000, 1961 to Unisys Clearpath/MCP, present.
- IBM OS/360 – IBM System/360, 1966 to IBM z/OS, present.
- IBM CP-67 – IBM System/360, 1967 to IBM z/VM, present.
- UNIVAC EXEC 8 – UNIVAC 1108, 1967, to OS 2200 Unisys Clearpath Dorado, present.

Microcomputers

PC DOS was an early personal computer OS that featured a command line interface. Mac OS by Apple Computer became the first widespread OS to feature a graphical user interface. Many of its features such as windows and icons would later become commonplace in GUIs.

The first microcomputers did not have the capacity or need for the elaborate operating systems that had been developed for mainframes and minis; minimalistic operating systems were developed, often loaded from ROM and known as

monitors. One notable early disk operating system was CP/M, which was supported on many early microcomputers and was closely imitated by Microsoft's MS-DOS, which became widely popular as the operating system chosen for the IBM PC (IBM's version of it was called IBM DOS or PC DOS). In the '80s, Apple Computer Inc. (now Apple Inc.) abandoned its popular Apple II series of microcomputers to introduce the Apple Macintosh computer with an innovative Graphical User Interface (GUI) to the Mac OS.

The introduction of the Intel 80386 CPU chip with 32-bit architecture and paging capabilities, provided personal computers with the ability to run multitasking operating systems like those of earlier minicomputers and mainframes. Microsoft responded to this progress by hiring Dave Cutler, who had developed the VMS operating system for Digital Equipment Corporation. He would lead the development of the Windows NT operating system, which continues to serve as the basis for Microsoft's operating systems line. Steve Jobs, a co-founder of Apple Inc., started NeXT Computer Inc., which developed the NEXTSTEP operating system. NEXTSTEP would later be acquired by Apple Inc. and used, along with code from FreeBSD as the core of Mac OS X.

The GNU Project was started by activist and programmer Richard Stallman with the goal of creating a complete free software replacement to the proprietary UNIX operating system. While the project was highly successful in duplicating the functionality of various parts of UNIX, development of the GNU Hurd kernel proved to be unproductive. In 1991, Finnish computer science student Linus Torvalds, with cooperation from volunteers collaborating over the Internet, released the first version of the Linux kernel. It was soon merged with the GNU user space components and system software to form a complete operating system. Since then, the combination of the two major components has usually been referred to as simply "Linux" by the software industry, a naming convention that Stallman and the Free Software Foundation remain opposed to, preferring the name GNU/Linux. The Berkeley Software Distribution, known as BSD, is the UNIX derivative distributed by the University of California, Berkeley, starting in the 1970s. Freely distributed and ported to many minicomputers, it eventually also gained a following for use on PCs, mainly as FreeBSD, NetBSD and OpenBSD